# **Product datasheet**

Specification





variable speed drive, Altivar Process ATV900, ATV930, 5.5kW, 200 to 240V, with braking unit, IP21

ATV930U55M3

# Main

Wall	
Range of product	Altivar Process ATV900
Device application	Industrial application
product or component type	Variable speed drive
product destination	Asynchronous motors
	Synchronous motors
Product specific application	Process for industrial
variant	Standard version
	With braking chopper
Network number of phases	3 phases
mounting mode	Wall mount
Communication port protocol	Modbus TCP
	EtherNet/IP
	Modbus serial
[Us] rated supply voltage	200240 V - 1510 %
Motor power kW	5.5 kW for normal duty
•	4.0 kW for heavy duty
Continuous output current	25.4 A at 4 kHz for normal duty
·	18.7 A at 4 kHz for heavy duty
EMC filter	Integrated
EMC IIItei	Integrated With EMC plate option
	That Ellio plate option
IP degree of protection	IP21
Degree of protection	UL type 1
option module	Slot A: communication module for Profibus DP V1
	Slot A: communication module for PROFINET
	Slot A: communication module for DeviceNet
	Slot A: communication module for EtherCAT
	Slot A: communication module for CANopen daisy chain RJ45
	Slot A: communication module for CANopen SUB-D 9
	Slot A: communication module for CANopen screw terminals
	Slot A/slot B/slot C: digital and analog I/O extension module
	Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module
	Slot B: analog encoder interface module
	Slot B: resolver encoder interface module
	communication module for Ethernet Powerlink
Discrete input logic	16 preset speeds
Asynchronous motor control	Variable torque standard
profile	Constant torque standard
•	Optimized torque mode
<del></del>	
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
maximum output frequency	333 TIZ

Switching frequency	216 kHz adjustable 416 kHz with derating factor
Nominal switching frequency	4 kHz
Line current	20.2 A at 200 V (normal duty)
	15.1 A at 200 V (heavy duty)
	17.1 A at 240 V (normal duty)
	13.0 A at 240 V (heavy duty)
Apparent power	7.6 kVA at 240 V (normal duty)
	6 kVA at 240 V (heavy duty)
Maximum transient current	30.5 A during 60 s (normal duty)
	28.1 A during 60 s (heavy duty)
Network frequency	5060 Hz
Prospective line Isc	50 kA

# Complementary

Somplementary		
Discrete input number	10	
Discrete input type	DI1DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 030 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm	
Discrete output number	2	
Discrete output type	Logic output DQ+ 01 kHz <= 30 V DC 100 mA  Programmable as pulse output DQ+ 030 kHz <= 30 V DC 20 mA  Logic output DQ- 01 kHz <= 30 V DC 100 mA	
Analogue input number	3	
Analogue input type	Al1, Al2, Al3 software-configurable voltage: 010 V DC, impedance: 30 kOhm, resolution 12 bits Al1, Al2, Al3 software-configurable current: 020 mA/420 mA, impedance: 250 Ohm, resolution 12 bits	
Analogue output number	2	
Analogue output type	Software-configurable voltage AQ1, AQ2: 010 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 020 mA impedance 500 Ohm, resolution 10 bits	
Relay output number	3	
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles	
Maximum switching current	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC	
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC	
Physical interface	Ethernet 2-wire RS 485	
Connector type	2 RJ45 1 RJ45	
Method of access	Slave Modbus TCP	
Transmission rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s	

Transmission from	DTU	
Transmission frame	RTU	
Number of addresses	1247	
Data format	8 bits, configurable odd, even or no parity	
Type of polarization	No impedance	
4 quadrant operation possible	True	
Acceleration and deceleration ramps	Linear adjustable separately from 0.019999 s	
Motor slip compensation	Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law	
Braking to standstill	By DC injection	
Brake chopper integrated	True	
Maximum input current	20.2 A	
Maximum output voltage	240.0 V	
Relative symmetric network frequency tolerance	5 %	
Base load current at high overload	18.7 A	
Base load current at low overload	25.4 A	
Power dissipation in W	Natural convection: 47 W at 200 V, switching frequency 4 kHz Forced convection: 179 W at 200 V, switching frequency 4 kHz	
With safety function Safely Limited Speed (SLS)	True	
With safety function Safe brake management (SBC/SBT)	True	
With safety function Safe Operating Stop (SOS)	False	
With safety function Safe Position (SP)	False	
With safety function Safe programmable logic	False	
With safety function Safe Speed Monitor (SSM)	False	
With safety function Safe Stop 1 (SS1)	True	
With sft fct Safe Stop 2 (SS2)	False	
With safety function Safe torque off (STO)	True	
With safety function Safely Limited Position (SLP)	False	
With safety function Safe Direction (SDI)	False	
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive	
Quantity per set	1	
Width	171 mm	

Height	409 mm
Depth	236 mm
net weight	7.7 kg
Electrical connection	Control: screw terminal 0.51.5 mm²/AWG 20AWG 16 Line side: screw terminal 6 mm²/AWG 10
	DC bus: screw terminal 6 mm²/AWG 10 Motor: screw terminal 10 mm²/AWG 8
Transmission rate	
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (1930 V), <1.25 mA, protection type:
	overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10
	mA, protection type: overload and short-circuit protection
	Internal supply for digital inputs and STO: 24 V DC (2127 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	Local diagnostic: 3 LED (mono/dual colour)
	Embedded communication status: 5 LED (dual colour)
	Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)
Input compatibility	DI1DI8: discrete input level 1 PLC conforming to IEC 61131-2
	DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68
	STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2
Discrete input logic	Positive logic (source) (DI1DI8), < 5 V (state 0), > 11 V (state 1)
	Negative logic (sink) (DI1DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1)
	Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Sampling duration	2 ms +/- 0.5 ms (DI1DI8) - discrete input
	5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input
	5 ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % Al1, Al2, Al3 for a temperature variation 60 °C analog input
<del></del>	+/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals
Environment	
Operating altitude	<= 1000 m without derating 10004800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	UL
	TÜV
	CSA
marking	CE
Standards	UL 508C IEC 61800-3
	IEC 61800-5-1
	IEC 61000-3-12 IEC 60721-3
	IEC 60721-3 IEC 61508
	IEC 13849-1

Manimum TUDI	18.07		
Maximum THDI	<48 % from 80100 % of load conforming to IEC 61000-3-12		
Assembly style	Enclosed		
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6		
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3		
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms		
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz		
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz		
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3		
Volume of cooling air	103 m3/h		
Overvoltage category	Ш		
Regulation loop	Adjustable PID regulator		
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth		
Noise level	56 dB conforming to 86/188/EEC		
Vibration resistance	1.5 mm peak to peak (f= 213 Hz) conforming to IEC 60068-2-6 1 gn (f= 13200 Hz) conforming to IEC 60068-2-6		
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27		
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to IEC 60721-3-3  Dust pollution resistance class 3S3 conforming to IEC 60721-3-3		
Relative humidity	595 % without condensation conforming to IEC 60068-2-3		
Ambient air temperature for operation	-1550 °C (without derating) 5060 °C (with derating factor)		
Noise level	56 dB		
Pollution degree	2		
Ambient air transport temperature	-4070 °C		
Ambient air temperature for storage	-4070 °C		
Packing Units			
Unit Type of Package 1	PCE		
Number of Units in Package 1	1		
Package 1 Height	34.700 cm		
Package 1 Width	21.500 cm		
Package 1 Length	58.000 cm		
Package 1 Weight	10.204 kg		
Unit Type of Package 2	P06		
Number of Units in Package 2	3		
Package 2 Height	75.000 cm		
Package 2 Width	60.000 cm		
Package 2 Length	80.000 cm		

Package 2 Weight

43.612 kg



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Transparency RoHS/REACh

# Resource performance



Upgraded Components Available

# Well-being performance



Mercury Free



Rohs Exemption Information

Yes

#### **Certifications & Standards**

Reach Regulation	REACh Declaration		
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)		
China Rohs Regulation	China RoHS declaration		
Environmental Disclosure	Product Environmental Profile		
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins		
Circularity Profile	End of Life Information		

# **Dimensions Drawings**

#### **Dimensions**

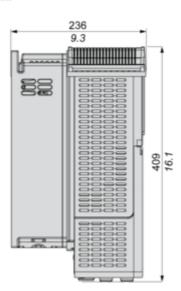
Front, Left and Rear View

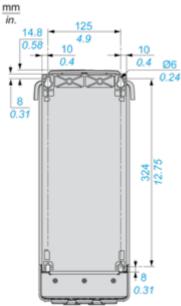
mm in.





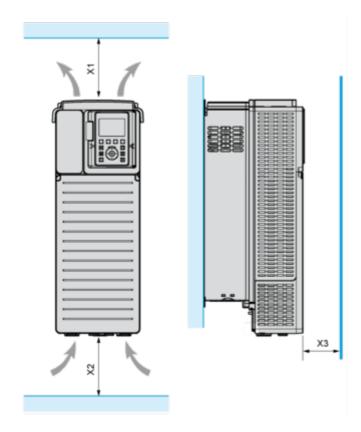






# Mounting and Clearance

#### Clearances

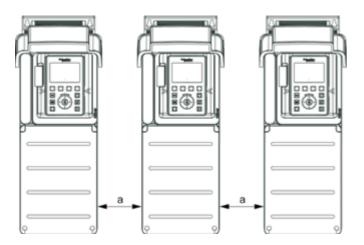


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- $_{\bullet}$  Mount the device in a vertical position (±10°). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

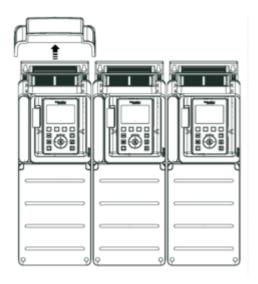
# **Mounting Types**

#### Mounting Type A: Individual IP21

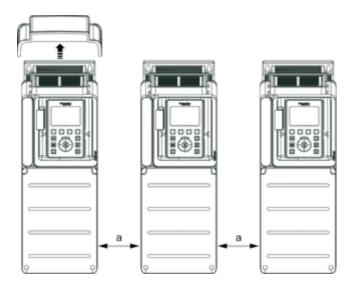


a ≥ 100 mm (3.94 in.)

# Mounting Type B: Side by Side IP20



Mounting Type C: Individual IP20

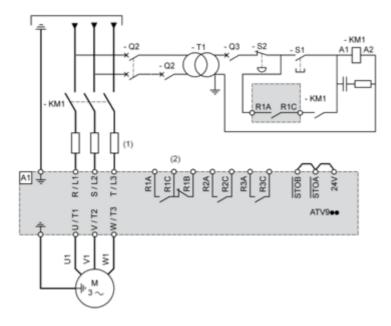


a ≥ 0

#### Connections and Schema

#### Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

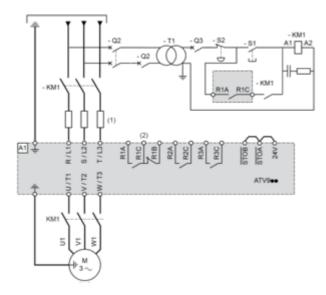
A1: Drive

KM1 : Line Contactor Q2, Q3 : Circuit breakers S1, S2 : Pushbuttons

T1 : Transformer for control part

# Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1

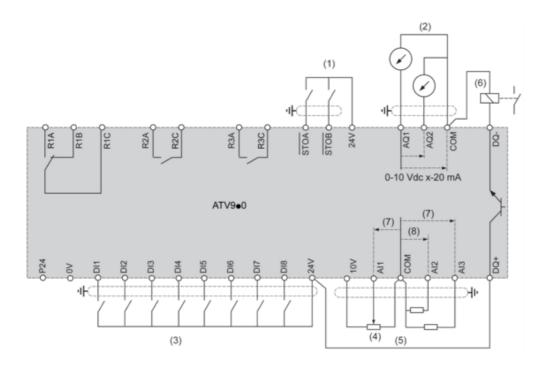


(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

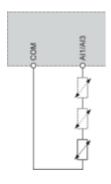
A1 : Drive KM1 : Contactor

# **Control Block Wiring Diagram**



- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- (6) Digital Output
- (7) 0-10 Vdc, x-20 mA
- (8) 0-10 Vdc, -10 Vdc...+10 Vdc R1A, R1B, R1C: Fault relay R2A, R2C: Sequence relay R3A, R3C: Sequence relay

# **Sensor Connection**



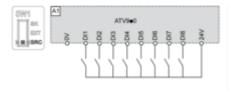
It is possible to connect either 1 or 3 sensors on terminals Al1 or Al3

#### Sink / Source Switch Configuration

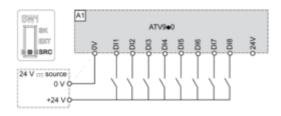
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

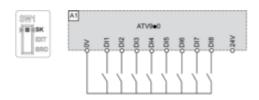
#### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



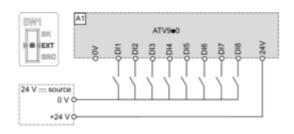
#### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



#### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs

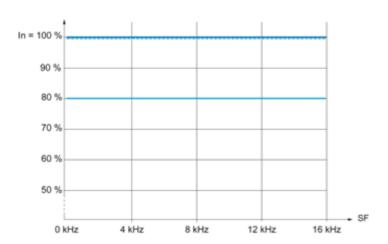


#### Switch Set to EXT Position Using an External Power Supply for the DIs



#### Performance Curves

#### **Derating Curves**



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In: Nominal Drive Current SF: Switching Frequency